# FRACTIONAL PROBLEMS WITH RIGHT-HANDED RIEMANN-LIOUVILLE FRACTIONAL DERIVATIVES <br> TADEUSZ JANKOWSKI 

## Department of Differential Equations and Applied Mathematics <br> Gdansk University of Technology <br> Narutowicza 11/12, 80-233 Gdansk, Poland

(received: 30 November 2015; revised: 23 December 2015;
accepted: 29 December 2015; published online: 22 February 2016)


#### Abstract

In this paper, we investigate the existence of solutions for advanced fractional differential equations containing the right-handed Riemann-Liouville fractional derivative both with nonlinear boundary conditions and also with initial conditions given at the end point $T$ of interval $[0, T]$. We use both the method of successive approximations, the Banach fixed point theorem and the monotone iterative technique, as well. Linear problems are also discussed. A few examples illustrate the results.


Keywords: right-handed Riemann-Liouville fractional derivatives, nonlinear boundary problems, linear problems, existence of solutions, Mittag-Leffler functions.

## 1. Introduction

Put $J_{0}=[0, T), J=[0, T]$. First, we introduce the right-handed RiemannLiouville fractional derivative $D_{T}^{q} x$ of order $q$ by

$$
\begin{equation*}
D_{T}^{q} x(t)=-\frac{1}{\Gamma(1-q)} \frac{d}{d t} \int_{t}^{T}(s-t)^{-q} x(s) d s, \quad t \in J_{0}, \quad q \in(0,1) \tag{1}
\end{equation*}
$$

and $D_{T}^{1} x(t)=-x^{\prime}(t)$, if $q=1$.
Similarly, we introduce the right-sided fractional integral $I_{T}^{q} x$ of order $q>0$ by

$$
\begin{equation*}
I_{T}^{q} x(t)=\frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1} x(s) d s, \quad t \in J_{0} \tag{2}
\end{equation*}
$$

The above definitions are taken from [1].

In this paper, we study the nonlinear boundary value problem of the form:

$$
\left\{\begin{array}{l}
D_{T}^{q} x(t)=f\left(t, x(t), x(\alpha(t)), \frac{1}{\Gamma\left(q_{1}\right)} \int_{t}^{T}(s-t)^{q_{1}-1} g(s) x(s) d s\right) \equiv F x(t), \quad t \in J_{0}  \tag{3}\\
0=h(\bar{x}(T))
\end{array}\right.
$$

where $f \in C(J \times \mathbb{R} \times \mathbb{R} \times \mathbb{R}, \mathbb{R}), \alpha \in C(J, J), g \in C(J, \mathbb{R}), h \in C(\mathbb{R}, \mathbb{R}), \bar{x}(T)=$ $\left.(T-t)^{1-q} x(t)\right|_{t=T}$ with $q \in(0,1], q_{1}>0$.

We introduce the space $C_{1-q}$ by

$$
\begin{equation*}
C_{1-q}(J, \mathbb{R})=\left\{u \in C([0, T), \mathbb{R}):(T-t)^{1-q} u \in C(J, \mathbb{R})\right\}, q \in(0,1) \tag{4}
\end{equation*}
$$

and $C_{0}(J, \mathbb{R})=C(J, \mathbb{R})$ if $q=1$.
Fractional differential equations arise in many engineering and scientific disciplines. Recently, much attention has been paid to study fractional differential equations. Some authors have formulated sufficient conditions under which fractional differential equations both with initial or boundary conditions have solutions. For example, such problems have been investigated for fractional differential equations with the left-handed Riemann-Liouville fractional derivative $D_{a+}^{q} x$ (or shortly $D^{q} x$ ) of order $q$, see for example $[2-8,1,9-20]$. An interesting and fruitful technique for proving the existence results for nonlinear fractional differential problems is the monotone iterative method based on lower and upper solutions, see for example [3-6, 9-14, 16-20]. Note that fractional differential equations with the right-handed RiemannLiouville fractional derivative $D_{T}^{q} x$ of order $q$ have been investigated, for example in $[21,1,15]$.

In our paper we use both the right-handed Riemann-Liouville fractional derivatives $D_{T}^{q} x$ and the right-sided fractional integrals $I_{T}^{q} x$ of order $q \in(0,1]$. If $g(s)=1, t \in J$, then, the fractional differential equation in problem (3) takes the form

$$
\begin{equation*}
D_{T}^{q} x(t)=f\left(t, x(t), x(\alpha(t)), I_{T}^{q_{1}} x(t)\right), \quad t \in J_{0} \tag{5}
\end{equation*}
$$

If $q_{1}=1$ and $g \in C(J, J)$ then, the fractional differential equation in problem (3) takes the following form

$$
\begin{equation*}
D_{T}^{q} x(t)=f\left(t, x(t), x(\alpha(t)), \int_{t}^{T} g(s) x(s) d s\right), \quad t \in J_{0} \tag{6}
\end{equation*}
$$

First we discuss initial problems with the initial condition given at the point $T$ for the fractional differential equations with $D_{T}^{q} x$ from (3) replacing this problem by a corresponding integral equation. Now, to find a unique solution, we apply the method of successive approximations assuming that function $f$ appearing in the right-hand-side of problem (3) satisfies a Lipschitz condition with respect to the last three variables. We also apply the Banach fixed point theorem with the Bielecki norm for the case $q=1$. The uniqueness of solutions is also investigated under the same Lipschitz condition. The linear fractional differential problems with initial conditions at the point $T$ are also investigated giving their solutions
in forms of Mittag-Leffler functions. Finally, to find a solution of problem (3), we use the monotone iterative method combined with lower and upper solutions. Indeed, we discuss also corresponding fractional differential inequalities. Some examples illustrate the results.

The organization of this paper is as follows. In Section 2, we discuss the nonlinear fractional differential equations of order $q$ with advanced arguments and with initial conditions given at the end point $T$ of interval $[0, T]$, see problem (10). We use the method of successive approximations to prove the existence and uniqueness result for problem (10) with $q \in(0,1)$, see Theorem 1. Example 1 illustrates the result of Theorem 1 . Theorem 2 concerns the existence and uniqueness of solutions of problem (3) for $q=1$, by using the Banach fixed point theorem with the Bielecki norm. In the next section, we study the uniqueness of solutions of problem (10) giving sufficient conditions under which problem (10) has at most one solution, see Theorem 3. Section 4 concerns linear fractional problems with initial conditions given at the point $T$. Theorem 4 presents the unique solution of such problems in terms of the Mittag-Leffler function. In Section 5, some examples are given. Examples 2 and 4 concern linear fractional problems while Example 3 the system of two linear fractional equations. In Sections 6 and 7 , we discuss the existence of solutions for general problems of type (3), by using the monotone iterative technique based on lower and upper solutions. The corresponding existence results are given by Theorem 5 for $q=1$, and Theorem 6 for $q \in(0,1)$. At the end of this paper, Example 5 concerns the application of Theorem 6 to a fractional differential equation with a nonlinear boundary condition.

## 2. Existence results for fractional problems with initial conditions

First, we cite a lemma.
Lemma 1 (see [1]). Let $0<q \leq 1, y \in L(0, T)$. Also let $y_{1-q}(t)=I_{T}^{1-q} y(t)$ be the fractional integral of order $1-q$ and $y_{1-q} \in A C[0, T]$. Then,

$$
\begin{equation*}
I_{T}^{q} D_{T}^{q} y(t)=y(t)-\frac{y_{1-q}(T)}{\Gamma(q)}(T-t)^{q-1} \quad \text { if } 0<q<1 \tag{7}
\end{equation*}
$$

and

$$
\begin{equation*}
I_{T}^{1} D_{T}^{1} y(t)=y(t)-y(T) \quad \text { if } q=1 \tag{8}
\end{equation*}
$$

Let us introduce the following assumption:
$H_{1}: f \in C(J \times \mathbb{R} \times \mathbb{R} \times \mathbb{R}, \mathbb{R}), \alpha \in C(J, J), \alpha(t) \geq t, g \in C(J, \mathbb{R})$ and there exist nonnegative constants $A, B, D$ such that

$$
\begin{equation*}
\left|f\left(t, u_{1}, u_{2}, u_{3}\right)-f\left(t, v_{1}, v_{2}, v_{3}\right)\right| \leq A\left|v_{1}-u_{1}\right|+B\left|v_{2}-u_{2}\right|+D\left|u_{3}-v_{3}\right| \tag{9}
\end{equation*}
$$

The next result concerns the problem:

$$
\left\{\begin{array}{l}
D_{T}^{q} u(t)=F u(t), \quad t \in J_{0}  \tag{10}\\
\bar{u}(T)=k \in \mathbb{R}
\end{array}\right.
$$

where operator $F$ is defined as in problem (3). Note that in (10) the initial point is given at the end point of interval $J$. Now, we formulate an existence result for problem (10).

Theorem 1. Let Assumption $H_{1}$ hold and let $q_{1}>0,0<q<1$. Moreover, we assume that there exists a constant $M>0$ such that

$$
\begin{equation*}
\frac{1}{\Gamma(q)} \sup _{t \in J_{0}} \int_{t}^{T}(s-t)^{q-1}\left|F u_{0}(s)\right| d s \leq M \tag{11}
\end{equation*}
$$

for $u_{0}(t)=k(T-t)^{q-1}$. Then, problem (10) has a unique solution $u \in C_{1-q}(J, \mathbb{R})$.
Proof. Using Lemma 1, it is easy to show that problem (10) is equivalent to the integral equation:

$$
\begin{equation*}
u(t)=k(T-t)^{q-1}+\frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1} F u(s) d s \tag{12}
\end{equation*}
$$

To find the solution of (12) we use the method of successive approximations. Let

$$
\left\{\begin{array}{l}
u_{0}(t)=k(T-t)^{q-1}  \tag{13}\\
u_{n}(t)=k(T-t)^{q-1}+I_{T}^{q} F u_{n-1}(t), \quad n=1,2, \cdots
\end{array}\right.
$$

Put

$$
\begin{equation*}
w_{n}(t)=\left|u_{n}(t)-u_{n-1}(t)\right|, n=1,2, \cdots, \quad L=A+B+\frac{D G}{\Gamma\left(q_{1}+1\right)} T^{q_{1}} \tag{14}
\end{equation*}
$$

with $G=\max _{t \in J}|g(t)|$. Then,

$$
\begin{align*}
w_{1}(t) & \leq \frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left|F u_{0}(s)\right| d s \leq M \\
w_{2}(t) & \leq \frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left|F u_{1}(s)-F u_{0}(s)\right| d s \\
& \leq \frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left[A w_{1}(s)+B w_{1}(\alpha(s))+\frac{D G}{\Gamma\left(q_{1}\right)} \int_{s}^{T}(\tau-s)^{q_{1}-1} w_{1}(\tau) d \tau\right] d s \\
& \leq \frac{M}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left[A+B+\frac{D G}{\Gamma\left(q_{1}\right)} \int_{s}^{T}(\tau-s)^{q_{1}-1} d \tau\right] d s \\
& \leq \frac{M L}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1} d s=\frac{M L}{\Gamma(q+1)}(T-t)^{q} \tag{15}
\end{align*}
$$

Now, we have to prove that

$$
\begin{equation*}
w_{n}(t) \leq \frac{M L^{n-1}}{\Gamma(q(n-1)+1)}(T-t)^{q(n-1)} \equiv z_{n}(t), \quad n=1,2, \cdots \tag{16}
\end{equation*}
$$

Assume that (16) holds for some integer $m>1$. As $\alpha(s) \geq s$, so $w_{m}(\alpha(s)) \leq z_{m}(s)$, and $w_{m}(\tau) \leq z_{m}(s), \tau \in[s, T]$. Using Assumption $H_{1}$ and relation (16) for $n=m$, we obtain

$$
\begin{align*}
w_{m+1} & (t) \leq \frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left|F u_{m}(s)-F u_{m-1}(s)\right| d s \\
& \leq \frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left[A w_{m}(s)+B w_{m}(\alpha(s))+\frac{D G}{\Gamma\left(q_{1}\right)} \int_{s}^{T}(\tau-s)^{q_{1}-1} w_{m}(\tau) d \tau\right] d s \\
& \leq \frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1} z_{m}(s)\left[A+B+\frac{D G}{\Gamma\left(q_{1}\right)} \int_{s}^{T}(\tau-s)^{q_{1}-1} d \tau\right] d s \\
& \leq \frac{L}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1} z_{m}(s) d s=\frac{M L^{m}}{\Gamma(q m+1)}(T-t)^{q m} \tag{17}
\end{align*}
$$

This and the mathematical induction show that (16) holds.
Now, we have to show that the sequence $\left\{u_{n}\right\}$ is convergent. First, we note that

$$
\begin{equation*}
u_{n}(t)=u_{0}(t)+\sum_{j=1}^{n}\left[u_{j}(t)-u_{j-1}(t)\right], \quad n=1,2, \cdots \tag{18}
\end{equation*}
$$

In view of (16), we see that

$$
\begin{align*}
\sum_{j=1}^{\infty} w_{j}(t) & \leq \sum_{j=1}^{\infty} \frac{M L^{j-1}}{\Gamma((j-1) q+1)}(T-t)^{(j-1) q}=M \sum_{j=0}^{\infty} \frac{L^{j}}{\Gamma(j q+1)}(T-t)^{j q} \\
& \leq M \sum_{j=0}^{\infty} \frac{L^{j}}{\Gamma(j q+1)} T^{j q}=M E_{q, 1}\left(L T^{q}\right) \tag{19}
\end{align*}
$$

where $E_{q, 1}$ is the Mittag-Leffler function defined by

$$
\begin{equation*}
E_{q, 1}(z)=\sum_{j=0}^{\infty} \frac{z^{j}}{\Gamma(j q+1)} \tag{20}
\end{equation*}
$$

It proves that $\lim _{n \rightarrow \infty} u_{n}(t)$ exists, so $u(t)=\lim _{n \rightarrow \infty} u_{n}(t)$. Indeed, $u-u_{0}$ is a continuous function on $J$ and $u$ is a continuous function on $J_{0}$. Taking the limit $n \rightarrow \infty$ in (13), we see that $u \in C_{1-q}(J, \mathbb{R})$ is a solution of problem (12).

Now we have to prove that $u$ is a unique solution of (12). Suppose that $v$ is another solution distinct from $u$ and such that $D_{0}=\sup _{t \in J_{0}} V(t)$ with $V(t)=|u(t)-v(t)|$. Then,

$$
\begin{align*}
V(t) & =\frac{1}{\Gamma(q)}\left|\int_{t}^{T}(s-t)^{q-1}[F u(s)-F v(s)] d s\right|  \tag{21}\\
& \leq \frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left[A V(s)+B V(\alpha(s))+\frac{D G}{\Gamma\left(q_{1}\right)} \int_{s}^{T}(\tau-s)^{q_{1}-1} V(\tau) d \tau\right] d s
\end{align*}
$$

by Assumption $H_{1}$. Then,

$$
\begin{equation*}
V(t) \leq \frac{D_{0} L}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1} d s=\frac{D_{0} L}{\Gamma(q+1)}(T-t)^{q} \leq \frac{D_{0} L}{\Gamma(q+1)} T^{q} \equiv D_{1} \tag{22}
\end{equation*}
$$

This and the previous relation on $V$ give

$$
\begin{align*}
V(t) & \leq \frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left[A V(s)+B V(\alpha(s))+\frac{D G}{\Gamma\left(q_{1}\right)} \int_{s}^{T}(\tau-s)^{q-1} V(\tau) d \tau\right] d s \\
& \leq \frac{D_{1} L}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1} d s=\frac{D_{1} L}{\Gamma(q+1)}(T-t)^{q} \tag{23}
\end{align*}
$$

Repeating it, we can show, by induction, that

$$
\begin{equation*}
V(t) \leq \frac{D_{1} L^{n}}{\Gamma(n q+1)}(T-t)^{n q}, \quad n=0,1, \cdots \tag{24}
\end{equation*}
$$

so

$$
\begin{equation*}
V(t) \leq \frac{D_{1} L^{n}}{\Gamma(n q+1)} T^{n q}, \quad n=0,1, \cdots \tag{25}
\end{equation*}
$$

Indeed,

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \frac{L^{n}}{\Gamma(n q+1)} T^{n q}=0 \tag{26}
\end{equation*}
$$

This shows that $u$ is the unique solution of (12). This also proves that $u$ is the unique solution of (10). This ends the proof.

Remark 1. Put $Z_{n}(t)=\left|u_{n}(t)-u(t)\right|$, where $u$ is the unique solution of problem (10) and $u_{n}$ is defined as in the proof of Theorem 1. Indeed, $Z_{0}(t) \leq$ $\max _{t \in J} Z_{0}(t) \equiv K$. Moreover,

$$
\begin{align*}
Z_{n}(t) \leq & \frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left|F u_{n-1}(s)-F u(s)\right| d s \\
\leq & \frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left[A Z_{n-1}(s)+B Z_{n-1}(\alpha(s))\right.  \tag{27}\\
& \left.+\frac{D G}{\Gamma\left(q_{1}\right)} \int_{s}^{T}(\tau-s)^{q_{1}-1} Z_{n-1}(\tau) d \tau\right] d s
\end{align*}
$$

for $n=1,2, \cdots$.
Similarly as in the proof of Theorem 1, we see that

$$
\begin{equation*}
\left|u_{n}(t)-u(t)\right| \leq \frac{K L^{n}}{\Gamma(n q+1)}(T-t)^{n q}, \quad n=0,1, \cdots \tag{28}
\end{equation*}
$$

The above relation gives the estimation between the approximate solution $u_{n}$ of problem (10) and the unique solution $u$ of problem (10).

Lemma 2. Assume that there exists a nonnegative constant $M_{1}$ such that

$$
\begin{align*}
& \text { (i) } \sup _{t \in J_{0}}\left|F u_{0}(t)\right| \leq M_{1}, \quad 0<q \leq \frac{1}{2} \\
& \text { (ii) } \sup _{t \in J_{0}}(T-t)^{1-q}\left|F u_{0}(t)\right| \leq M_{1}, \quad \frac{1}{2}<q<1 \tag{29}
\end{align*}
$$

Then, condition (11) holds.

Proof. Case 1. Assume that $0<q \leq \frac{1}{2}$. Indeed,

$$
\begin{equation*}
\frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left|F u_{0}(s)\right| d s \leq \frac{M_{1}}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1} d s \leq \frac{M_{1}}{\Gamma(q+1)} T^{q} \equiv M \tag{30}
\end{equation*}
$$

Case 2. Let $\frac{1}{2}<q<1$. Using the Schwartz inequality for integrals, we have

$$
\begin{align*}
\int_{t}^{T}(s-t)^{q-1}(T-s)^{q-1} d s & \leq \sqrt{\int_{t}^{T}(s-t)^{2(q-1)} d s} \sqrt{\int_{t}^{T}(T-s)^{2(q-1)} d s}  \tag{31}\\
& =\frac{\Gamma(2 q-1)}{\Gamma(2 q)}(T-t)^{2 q-1} \leq \frac{\Gamma(2 q-1)}{\Gamma(2 q)} T
\end{align*}
$$

Hence,

$$
\begin{align*}
\frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left|F u_{0}(s)\right| d s & =\frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}(T-s)^{q-1}(T-s)^{1-q}\left|F u_{0}(s)\right| d s \\
& \leq \frac{M_{1}}{\Gamma(q)} \frac{\Gamma(2 q-1)}{\Gamma(2 q)} T \equiv M \tag{32}
\end{align*}
$$

This ends the proof.
Remark 2. For example, in papers [2, 15] the assumption

$$
\begin{equation*}
\sup _{t \in J_{1}}|f(t, y)| \leq M \tag{33}
\end{equation*}
$$

has been used for in initial value problem:

$$
\begin{cases}D^{q} x(t)=f(t, x(t)), & t \in J_{1}=(0, T], q \in(0,1]  \tag{34}\\ \bar{x}(0)=k, \quad \bar{x}(0)=\left.t^{1-q} x(t)\right|_{t=0} & \end{cases}
$$

Example 1. Consider the following nonlinear fractional differential problem:

$$
\left\{\begin{array}{l}
D_{T}^{q} x(t)=\lambda \sin x(t)+\sigma(t), \quad t \in J_{0}=[0, T)  \tag{35}\\
\bar{x}(T)=k
\end{array}\right.
$$

where $\lambda, k \in \mathbb{R}, \sigma \in C(J, \mathbb{R})$. Note that all assumptions of Theorem 1 hold with

$$
\begin{equation*}
A=|\lambda|, \quad B=D=0, \quad M=\frac{T^{q}}{\Gamma(q+1)}\left[\max _{t \in J}|\sigma(t)|+|\lambda|\right] \tag{36}
\end{equation*}
$$

In view of Theorem 1, problem (35) has a unique solution $x$ being the limit of the sequence $\left\{x_{n}\right\}$ defined by

$$
\left\{\begin{array}{l}
x_{0}(t)=k(T-t)^{q-1}  \tag{37}\\
x_{n+1}(t)=k(T-t)^{q-1}+\frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left[\lambda \sin x_{n}(s)+\sigma(s)\right] d s
\end{array}\right.
$$

for $n=0,1, \cdots$. Moreover

$$
\begin{equation*}
\left|x(t)-x_{n}(t)\right| \leq \frac{K L^{n}}{\Gamma(n q+1)}(T-t)^{n q}, \quad n=0,1, \cdots \tag{38}
\end{equation*}
$$

by Remark 1. Here $L=|\lambda|, K=M$.

Now, we consider the case $q=1$, so problem (10) takes the form

$$
\left\{\begin{array}{l}
u^{\prime}(t)=-F u(t), \quad t \in J  \tag{39}\\
u(T)=k \in \mathbb{R}
\end{array}\right.
$$

Theorem 2. Let $q=1, q_{1}>0$. Suppose that Assumption $H_{1}$ holds. Then, problem (39) has a unique solution $u \in C^{1}(J, \mathbb{R})$.

Proof. Note that problem (39) is equivalent to the following one

$$
\begin{equation*}
u(t)=k+\int_{t}^{T} F u(s) d s \equiv A u(t), \quad t \in J \tag{40}
\end{equation*}
$$

Put

$$
\begin{equation*}
\|u\|_{*}=\max _{t \in J} e^{\lambda(t-T)}|u(t)| \text { for } \lambda \geq L, \lambda>0, \text { and } Q=\left(1-e^{-\lambda T}\right)<1 \tag{41}
\end{equation*}
$$

where $L$ is defined as in the proof of Theorem 1 . We show that operator $A$ is a contraction with the Bielecki norm $\|\cdot\|_{*}$. Let $u, v \in C(J, \mathbb{R})$. Then, in view of Assumption $H_{1}$, we obtain

$$
\begin{align*}
\| A u- & A v \|_{*} \leq \max _{t \in J} e^{\lambda(t-T)} \int_{t}^{T}|F u(s)-F v(s)| d s \\
\leq & \max _{t \in J} e^{\lambda(t-T)} \int_{t}^{T}[A|u(s)-v(s)|+B|u(\alpha(s))-v(\alpha(s))| \\
& \left.+\frac{D G}{\Gamma\left(q_{1}\right)} \int_{s}^{T}(\tau-s)^{q_{1}-1}|u(\tau)-v(\tau)| d \tau\right] d s  \tag{42}\\
\leq & \|u-v\|_{*} \max _{t \in J} e^{\lambda t} \int_{t}^{T}\left[A e^{-\lambda s}+B e^{-\lambda \alpha(s)}+\frac{D G}{\Gamma\left(q_{1}\right)} \int_{s}^{T}(\tau-s)^{q_{1}-1} e^{-\lambda \tau} d \tau\right] d s \\
\leq & \|u-v\|_{*} L \max _{t \in J} e^{\lambda t} \int_{t}^{T} e^{-\lambda s} d s \\
= & \frac{L}{\lambda} Q\|u-v\|_{*} \leq Q\|u-v\|_{*}
\end{align*}
$$

Then, problem (39) has a unique solution, by the Banach fixed point theorem. This ends the proof.

Remark 3. To show that problem (10) with $q \in(0,1)$ has a unique solution we can also use the Banach fixed point theorem with a corresponding norm using the Hölder inequality for integrals.

## 3. Uniqueness of solutions of problem (10)

Basing on the proof of Theorem 1, we can formulate some sufficient conditions for the uniqueness of the solution of problem (10) but it does not guarantee the existence of this solution.

Theorem 3. Let Assumption $H_{1}$ hold and let $q_{1}>0,0<q<1$.
Then, problem (10) has at most one solution in the space $C_{1-q}(J, \mathbb{R})$.

Proof. Note that $u$ is a solution of (10) if and only if

$$
\begin{equation*}
u(t)=k(T-t)^{q-1}+I_{T}^{q} F u(t) \tag{43}
\end{equation*}
$$

Assume that the above problem has two distinct solutions $U, V \in C_{1-q}(J, \mathbb{R})$ and put $P(t)=|U(t)-V(t)|, P_{0}=\sup _{t \in J_{0}} P(t)$. Then, using Assumption $H_{1}$, we obtain

$$
\begin{align*}
P(t) & \leq I_{T}^{q}|F U(t)-F V(t)| \\
& \leq \frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left[A P(s)+B P(\alpha(s))+\frac{D G}{\Gamma\left(q_{1}\right)} \int_{s}^{T}(\tau-s)^{q_{1}-1} P(\tau) d \tau\right] d s \\
& \leq P_{0} \frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left[A+B+\frac{D G}{\Gamma\left(q_{1}\right)} \int_{s}^{T}(\tau-s)^{q_{1}-1} d \tau\right] d s \\
& \leq \frac{P_{0} L}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1} d s=\frac{P_{0} L}{\Gamma(q+1)}(T-t)^{q} \leq \frac{P_{0} L}{\Gamma(q+1)} T^{q} \equiv P_{1} \tag{44}
\end{align*}
$$

where $L$ is defined as in Theorem 1. Now, similarly as in the proof of Theorem 1, we can show

$$
\begin{equation*}
P(t) \leq \frac{P_{1} L^{n}}{\Gamma(n q+1)} T^{n q}, \quad n=0,1, \cdots \tag{45}
\end{equation*}
$$

Hence, the assertion holds because

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \frac{P_{1} L^{n}}{\Gamma(n q+1)} T^{n q}=0 \tag{46}
\end{equation*}
$$

## 4. Linear fractional differential equations

Let us consider the following linear problem

$$
\begin{equation*}
D_{T}^{q} x(t)=\lambda I_{T}^{q_{1}} x(t)+\sigma(t), \quad t \in J_{0}, \bar{x}(T)=k, \tag{47}
\end{equation*}
$$

where $\lambda, k \in \mathbb{R}, \sigma \in C_{1-q}(J, \mathbb{R})$.
Theorem 4. Let $q \in(0,1], q_{1}>0, \lambda, k \in \mathbb{R}, \sigma \in C_{1-q}(J, \mathbb{R})$. Then, problem (47) has a unique solution given by the formula

$$
\begin{align*}
x(t)= & k \Gamma(q)(T-t)^{q-1} E_{q+q_{1}, q}\left(\lambda(T-t)^{q+q_{1}}\right) \\
& +\int_{t}^{T}(s-t)^{q-1} E_{q+q_{1}, q}\left(\lambda(s-t)^{q+q_{1}}\right) \sigma(s) d s \tag{48}
\end{align*}
$$

where $E_{\nu, \beta}(\zeta)=\sum_{r=0}^{\infty} \frac{\zeta^{r}}{\Gamma(\nu r+\beta)}$ is the Mittag-Leffler function.
Proof. Indeed, problem (47) is equivalent in the space $C_{1-q}(J, \mathbb{R})$ to the following fractional integral equation

$$
\begin{equation*}
x(t)=x_{0}(t)+\lambda I_{T}^{q+q_{1}} x(t)+I_{T}^{q} \sigma(t), \quad t \in J_{0} \tag{49}
\end{equation*}
$$

where $x_{0}(t)=k(T-t)^{q-1}$.

We apply the method of successive approximations to find the solution of problem (49), so for $n=0,1, \cdots$, we have

$$
\begin{equation*}
x_{n+1}(t)=x_{0}(t)+\lambda I_{T}^{q+q_{1}} x_{n}(t)+I_{T}^{q} \sigma(t) \tag{50}
\end{equation*}
$$

Hence,

$$
\begin{align*}
x_{1}(t) & =x_{0}(t)+\lambda I_{T}^{q+q_{1}} x_{0}(t)+I_{T}^{q} \sigma(t) \\
x_{2}(t) & =x_{0}(t)+\lambda I_{T}^{q+q_{1}} x_{1}(t)+I_{T}^{q} \sigma(t) \\
& =x_{0}(t)+\lambda I_{T}^{q+q_{1}}\left[x_{0}(t)+\lambda I_{T}^{q+q_{1}} x_{0}(t)+I_{T}^{q} \sigma(t)\right]+I_{T}^{q} \sigma(t)  \tag{51}\\
& =x_{0}(t)+\lambda I_{T}^{q+q_{1}} x_{0}(t)+\lambda^{2} I_{T}^{2\left(q+q_{1}\right)} x_{0}(t)+\lambda I_{T}^{2 q+q_{1}} \sigma(t)+I_{T}^{q} \sigma(t)
\end{align*}
$$

using the relation $I_{T}^{r} I_{T}^{m} x(t)=I_{T}^{r+m} x(t), r, m>0$.
Thus, in general, we get by induction $x_{n}$ as follows

$$
\begin{equation*}
x_{n}(t)=x_{0}(t)+\sum_{i=1}^{n} \lambda^{i} I_{T}^{i\left(q+q_{1}\right)} x_{0}(t)+\sum_{i=1}^{n} \lambda^{i-1} I_{T}^{(i-1)\left(q+q_{1}\right)+q} \sigma(t), \quad n=1,2, \cdots \tag{52}
\end{equation*}
$$

Using the following formula

$$
\begin{equation*}
I_{T}^{\delta} x_{0}(t)=x_{0}(t) \frac{\Gamma(q)}{\Gamma(\delta+q)}(T-t)^{\delta}, \quad \delta>0 \tag{53}
\end{equation*}
$$

to (52), we obtain

$$
\begin{align*}
x_{n}(t)= & x_{0}(t)\left[1+\Gamma(q) \sum_{i=1}^{n} \lambda^{i} \frac{1}{\Gamma\left(i\left(q+q_{1}\right)+q\right)}(T-t)^{i\left(q+q_{1}\right)}\right] \\
& +\sum_{i=1}^{n} \lambda^{i-1} \frac{1}{\Gamma\left((i-1)\left(q+q_{1}\right)+q\right)} \int_{t}^{T}(s-t)^{(i-1)\left(q+q_{1}\right)+q-1} \sigma(s) d s  \tag{54}\\
= & x_{0}(t) \Gamma(q) \sum_{i=0}^{n} \lambda^{i} \frac{1}{\Gamma\left(i\left(q+q_{1}\right)+q\right)}(T-t)^{i\left(q+q_{1}\right)} \\
& +\int_{t}^{T}(s-t)^{q-1}\left[\sum_{i=0}^{n-1} \lambda^{i} \frac{1}{\Gamma\left(i\left(q+q_{1}\right)+q\right)}(s-t)^{i\left(q+q_{1}\right)}\right] \sigma(s) d s
\end{align*}
$$

for $n=0,1, \cdots$. Taking the limit as $n \rightarrow \infty$, we obtain the unique solution $x$ in terms of the Mittag-Lefller function given by formula (48).

Remark 4. Put $q=1$, then, problem (47) takes the form

$$
\begin{equation*}
-x^{\prime}(t)=\lambda I_{T}^{q_{1}} x(t)+\sigma(t), \quad t \in J_{0}, x(T)=k \tag{55}
\end{equation*}
$$

Let $q_{1}=1, \lambda=1$. Then, $E_{2,1}\left(t^{2}\right)=\cosh (t)$, so, in view of (48), the solution has the form

$$
\begin{equation*}
x(t)=k \cosh (T-t)+\int_{t}^{T} \cosh (s-t) \sigma(s) d s \tag{56}
\end{equation*}
$$

## 5. Examples

In this section, some examples are given.
Example 2. For $q \in(0,1], q_{1}>0$, let us consider the following problem

$$
\left\{\begin{array}{l}
D_{T}^{q} x(t)=I_{T}^{q_{1}} x(t)-\frac{\Gamma(q)}{\Gamma\left(q+q_{1}\right)}(T-t)^{q+q_{1}-1}, \quad t \in J_{0}=[0, T)  \tag{57}\\
\bar{x}(T)=1
\end{array}\right.
$$

Comparing this problem with (47) we see that

$$
\begin{equation*}
\lambda=1, \quad \sigma(t)=-\frac{\Gamma(q)}{\Gamma\left(q+q_{1}\right)}(T-t)^{q+q_{1}-1}, \quad k=1 \tag{58}
\end{equation*}
$$

In view of Theorem 4, problem (57) has a unique solution given by

$$
\begin{align*}
x(t)= & \Gamma(q)(T-t)^{q-1} E_{q+q_{1}, q}\left((T-t)^{q+q_{1}}\right)+\int_{t}^{T}(s-t)^{q-1} E_{q+q_{1}, q}\left((s-t)^{q+q_{1}}\right) \sigma(s) d s \\
= & \Gamma(q)(T-t)^{q-1} E_{q+q_{1}, q}\left((T-t)^{q+q_{1}}\right) \\
& -\frac{\Gamma(q)}{\Gamma\left(q+q_{1}\right)} \sum_{n=0}^{\infty} \frac{1}{\Gamma\left(n\left(q+q_{1}\right)+q\right)} \int_{t}^{T}(s-t)^{n\left(q+q_{1}\right)+q-1}(T-s)^{q+q_{1}-1} d s \\
= & \Gamma(q)(T-t)^{q-1} E_{q+q_{1}, q}\left((T-t)^{q+q_{1}}\right) \\
& -\Gamma(q) \sum_{n=0}^{\infty} \frac{1}{\Gamma\left((n+1)\left(q+q_{1}\right)+q\right)}(T-t)^{(n+1)\left(q+q_{1}\right)+q-1}  \tag{59}\\
= & \Gamma(q)(T-t)^{q-1}\left[E_{q+q_{1}, q}\left((T-t)^{q+q_{1}}\right)-\sum_{n=1}^{\infty} \frac{1}{\Gamma\left(n\left(q+q_{1}\right)+q\right)}(T-t)^{n\left(q+q_{1}\right)}\right] \\
= & \Gamma(q)(T-t)^{q-1}\left[E_{q+q_{1}, q}\left((T-t)^{q+q_{1}}\right)-E_{q+q_{1}, q}\left((T-t)^{q+q_{1}}\right)+\frac{1}{\Gamma(q)}\right] \\
= & (T-t)^{q-1}
\end{align*}
$$

It proves that $x(t)=(T-t)^{q-1}$ is the unique solution of problem (57).
Example 3. Consider the system of fractional linear equations:

$$
\begin{cases}D_{T}^{q} x(t)=2 I_{T}^{q_{1}} x(t)-2 I_{T}^{q_{1}} y(t)+\sigma_{1}(t), & t \in J_{0}=[0, T)  \tag{60}\\ D_{T}^{q} y(t)=-2 I_{T}^{q_{1}} x(t)+2 I_{T}^{q_{1}} y(t)+\sigma_{2}(t), & t \in J_{0} \\ \bar{x}(T)=1, \quad \bar{y}(T)=0 & \end{cases}
$$

with $q \in(0,1), q_{1}>0$ and

$$
\begin{align*}
\sigma_{1}(t)= & -\frac{2 \Gamma(q)}{\Gamma\left(q+q_{1}\right)}(T-t)^{q+q_{1}-1}+\frac{10}{\Gamma\left(2+q_{1}\right)}(T-t)^{1+q_{1}}+\frac{4}{\Gamma(3-q)}(T-t)^{2-q} \\
\sigma_{2}(t)= & \frac{2 \Gamma(q)}{\Gamma\left(q+q_{1}\right)}(T-t)^{q+q_{1}-1}-\frac{10}{\Gamma\left(2+q_{1}\right)}(T-t)^{1+q_{1}}+\frac{4}{\Gamma(3-q)}(T-t)^{2-q}  \tag{61}\\
& +\frac{5}{\Gamma(2-q)}(T-t)^{1-q}
\end{align*}
$$

Put $P=x+y, Q=x-y$. Then, in view of (60), we obtain

$$
\left\{\begin{array}{l}
D_{T}^{q} P(t)=\sigma_{1}(t)+\sigma_{2}(t), \quad t \in J_{0}  \tag{62}\\
\bar{P}(T)=1
\end{array}\right.
$$

$$
\left\{\begin{array}{l}
D_{T}^{q} Q(t)=4 I_{T}^{q_{1}} Q(t)+\sigma_{1}(t)-\sigma_{2}(t)  \tag{63}\\
\bar{Q}(T)=1
\end{array}\right.
$$

In view of (48), the solution $P$ of problem (62) is given by

$$
\begin{align*}
P(t) & =(T-t)^{q-1}+\frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left[\sigma_{1}(s)+\sigma_{2}(s)\right] d s \\
& =(T-t)^{q-1}+\frac{1}{\Gamma(q)} \int_{t}^{T}(s-t)^{q-1}\left[\frac{8}{\Gamma(3-q)}(T-s)^{2-q}+\frac{5}{\Gamma(2-q)}(T-s)^{1-q}\right] d s \\
& =(T-t)^{q-1}+4(T-t)^{2}+5(T-t) \tag{64}
\end{align*}
$$

Similarly, for $Q$ we have

$$
\begin{align*}
Q(t)= & \Gamma(q)(T-t)^{q-1} E_{q+q_{1}, q}\left(4(T-t)^{q+q_{1}}\right) \\
& +\int_{t}^{T}(s-t)^{q-1} E_{q+q_{1}, q}\left(4(s-t)^{q+q_{1}}\right)\left[\sigma_{1}(s)-\sigma_{2}(s)\right] d s \\
= & \Gamma(q)(T-t)^{q-1} E_{q+q_{1}, q}\left(4(T-t)^{q+q_{1}}\right) \\
& +\sum_{r=0}^{\infty} \frac{4^{r}}{\Gamma\left(r\left(q+q_{1}\right)+q\right)} \int_{t}^{T}(s-t)^{r\left(q+q_{1}\right)+q-1}\left[-\frac{4 \Gamma(q)}{\Gamma\left(q+q_{1}\right)}(T-s)^{q+q_{1}-1}\right. \\
& \left.+\frac{20}{\Gamma\left(2+q_{1}\right)}(T-s)^{1+q_{1}}-\frac{5}{\Gamma(2-q)}(T-s)^{1-q}\right] \\
= & \Gamma(q)(T-t)^{q-1} E_{q+q_{1}, q}\left(4(T-t)^{q+q_{1}}\right) \\
& -\Gamma(q) \sum_{r=0}^{\infty} \frac{4^{r+1}}{\Gamma\left((r+1)\left(q+q_{1}\right)+q\right)}(T-t)^{(r+1)\left(q+q_{1}\right)+q-1} \\
& +5 \sum_{r=0}^{\infty} \frac{4^{r+1}}{\Gamma\left((r+1)\left(q+q_{1}\right)+2\right)}(T-t)^{(r+1)\left(q+q_{1}\right)+1} \\
& -5 \sum_{r=0}^{\infty} \frac{4^{r}}{\Gamma\left(r\left(q+q_{1}\right)+2\right)}(T-t)^{r\left(q+q_{1}\right)+1} \\
= & \Gamma(q)(T-t)^{q-1} E_{q+q_{1}, q}\left(4(T-t)^{q+q_{1}}\right) \\
& -\Gamma(q)(T-t)^{q-1}\left[E_{q+q_{1}, q}\left(4(T-t)^{q+q_{1}}\right)-\frac{1}{\Gamma(q)}\right] \\
& +5(T-t)\left[E_{q+q_{1}, 2}\left(4(T-t)^{q+q_{1}}\right)-1\right]-5(T-t) E_{q+q_{1}, 2}\left(4(T-t)^{q+q_{1}}\right) \\
= & (T-t)^{q-1}-5(T-t) \tag{65}
\end{align*}
$$

Now, solving the system:

$$
\left\{\begin{array}{l}
x(t)+y(t)=(T-t)^{q-1}+4(T-t)^{2}+5(T-t)  \tag{66}\\
x(t)-y(t)=(T-t)^{q-1}-5(T-t)
\end{array}\right.
$$

we see that the solution $(x, y)$ of $(60)$ is given by

$$
\left\{\begin{array}{l}
x(t)=(T-t)^{q-1}+2(T-t)^{2}  \tag{67}\\
y(t)=2(T-t)^{2}+5(T-t)
\end{array}\right.
$$

Example 4. Consider the problem:

$$
\left\{\begin{array}{l}
D_{T}^{q} x(t)=\lambda \frac{1}{\Gamma\left(q_{1}\right)} \int_{t}^{T}(s-t)^{q_{1}-1}(T-s)^{r} x(s) d s, \quad t \in J_{0}=[0, T)  \tag{68}\\
\bar{x}(T)=k
\end{array}\right.
$$

where $\lambda, k \in \mathbb{R}, r>-q, q_{1}>0$; so $g(s)=(T-s)^{r}$ in comparing with the operator $F$ from problem (3). Problem (68) is equivalent to the integral equation

$$
\begin{equation*}
x(t)=k(T-t)^{q-1}+\frac{\lambda}{\Gamma(q) \Gamma\left(q_{1}\right)} \int_{t}^{T}(s-t)^{q-1}\left[\int_{s}^{T}(\tau-s)^{q_{1}-1}(T-\tau)^{r} x(\tau) d \tau\right] d s . \tag{69}
\end{equation*}
$$

To find a solution of (69) we use the method of successive approximation, so

$$
\left\{\begin{array}{l}
x_{0}(t)=k(T-t)^{q-1}  \tag{70}\\
x_{n+1}(t)=x_{0}(t)+\frac{\lambda}{\Gamma(q) \Gamma\left(q_{1}\right)} \int_{t}^{T}(s-t)^{q-1}\left[\int_{s}^{T}(\tau-s)^{q_{1}-1}(T-\tau)^{r} x_{n}(\tau) d \tau\right] d s
\end{array}\right.
$$

for $n=0,1, \cdots$.
Indeed,

$$
\begin{align*}
x_{1}(t) & =x_{0}(t)+\frac{\lambda k}{\Gamma(q) \Gamma\left(q_{1}\right)} \int_{t}^{T}(s-t)^{q-1}\left[\int_{s}^{T}(\tau-s)^{q_{1}-1}(T-\tau)^{r+q-1} d \tau\right] d s \\
& =x_{0}(t)+\frac{\lambda k}{\Gamma(q)} \frac{\Gamma(r+q)}{\Gamma\left(r+q+q_{1}\right)} \int_{t}^{T}(s-t)^{q-1}(T-s)^{r+q+q_{1}-1} d s  \tag{71}\\
& =x_{0}(t)\left[1+\lambda \frac{\Gamma(r+q)}{\Gamma\left(2 q+r+q_{1}\right)}(T-t)^{q+r+q_{1}}\right]
\end{align*}
$$

and

$$
\begin{align*}
x_{2}(t)= & x_{0}(t)+\frac{\lambda}{\Gamma(q) \Gamma\left(q_{1}\right)} \int_{t}^{T}(s-t)^{q-1}\left[\int_{s}^{T}(\tau-s)^{q_{1}-1}(T-\tau)^{r} x_{1}(\tau) d \tau\right] d s \\
= & x_{0}(t)+\frac{\lambda k}{\Gamma(q) \Gamma\left(q_{1}\right)} \int_{t}^{T}(s-t)^{q-1}\left[\int_{s}^{T}(\tau-s)^{q_{1}-1}(T-\tau)^{r+q-1} d \tau\right. \\
& \left.+\lambda \frac{\Gamma(r+q)}{\Gamma\left(2 q+r+q_{1}\right)} \int_{s}^{T}(\tau-s)^{q_{1}-1}(T-\tau)^{2 r+2 q+q_{1}-1} d \tau\right] d s \\
= & x_{0}(t)+\frac{\lambda k}{\Gamma(q)} \frac{\Gamma(r+q)}{\Gamma\left(q+r+q_{1}\right)} \int_{t}^{T}(s-t)^{q-1}(T-s)^{r+q+q_{1}-1} d s \\
& +\frac{\lambda^{2} k}{\Gamma(q)} \frac{\Gamma(r+q) \Gamma\left(2 r+2 q+q_{1}\right)}{\Gamma\left(2 q+r+q_{1}\right) \Gamma\left(2\left(r+q+q_{1}\right)\right)} \int_{t}^{T}(s-t)^{q-1}(T-s)^{2 q+2 q_{1}+2 r-1} d s \\
= & x_{0}(t)\left[1+\lambda \frac{\Gamma(q+r)}{\Gamma\left(2 q+r+q_{1}\right)}(T-t)^{q+r+q_{1}}\right. \\
& \left.+\Lambda^{2} \frac{\Gamma(q+r) \Gamma\left(2(q+r)+q_{1}\right)}{\Gamma\left(2 q+r+q_{1}\right) \Gamma\left(3 q+2\left(r+q_{1}\right)\right.}(T-t)^{2\left(q+r+q_{1}\right)}\right] \tag{72}
\end{align*}
$$

By induction, we can show

$$
\begin{equation*}
x_{n}(t)=x_{0}(t) \sum_{j=0}^{n} \lambda^{j} c_{j}(T-t)^{j\left(q+r+q_{1}\right)}, \quad n=1,2, \cdots \tag{73}
\end{equation*}
$$

where

$$
\begin{equation*}
c_{0}=1, \quad c_{j}=\prod_{i=0}^{j-1} \frac{\Gamma\left(i\left(q+r+q_{1}\right)+q+r\right)}{\Gamma\left((i+1)\left(q+r+q_{1}\right)+q\right)}, \quad j=1,2, \cdots \tag{74}
\end{equation*}
$$

Now, taking the limit as $n \rightarrow \infty$, we obtain a solution of (68), by formula:

$$
\begin{equation*}
x(t)=k(T-t)^{q-1} \sum_{j=0}^{\infty} c_{j}\left[\lambda(T-t)^{\left(q+r+q_{1}\right)}\right]^{j} \tag{75}
\end{equation*}
$$

This solution of (68) can be written in the form

$$
\begin{equation*}
x(t)=k(T-t)^{q-1} E_{q+q_{1}, 1+\frac{r}{q+q_{1}}, 1+\frac{r-1-q_{1}}{q+q_{1}}}\left[\lambda(T-t)^{\left(q+r+q_{1}\right)}\right] \tag{76}
\end{equation*}
$$

where $E_{\nu, m, n}$ is the Mittag-Leffler function given by

$$
\begin{equation*}
E_{\nu, m, n}(z)=\sum_{j=0}^{\infty} c_{j}^{*} z^{j} \tag{77}
\end{equation*}
$$

with

$$
\begin{equation*}
c_{0}^{*}=1, \quad c_{j}^{*}=\prod_{i=0}^{j-1} \frac{\Gamma(\nu(i m+n)+1)}{\Gamma(\nu(i m+n+1)+1)}, \quad j=1,2, \cdots \tag{78}
\end{equation*}
$$

see p. 48 of [1]. Indeed, $c_{j}=c_{j}^{*}$ for $\nu=q+q_{1}, m=1+\frac{r}{q+q_{1}}, n=1+\frac{r-1-q_{1}}{q+q_{1}}$. If $r \geq 0$, then, $x$ given by (76) is the unique solution of (68), by Theorem 1 . Note that if $r=0$, then, $c_{j}=\frac{\Gamma(q)}{\Gamma\left(j\left(q+q_{1}\right)+q\right)}$ and $E_{q+q_{1}, 1, \frac{q-1}{q+q_{1}}}(z)=E_{q+q_{1}, q}(z)$.

## 6. Existence results for fractional problems of type (3) with $q=1$

In this section, we consider the existence of extremal solutions of problem (3) in the case $q=1$. To obtain it, we apply the monotone iterative technique, therefore we first formulate a comparison result which will play a very important role in our research.

Lemma 3. Let $\alpha \in C(J, J), t \leq \alpha(t) \leq T$ on $J$. Suppose that $M \in C(J, \mathbb{R})$, $p \in C^{1}(J, \mathbb{R})$ and

$$
\left\{\begin{array}{l}
p^{\prime}(t) \geq M(t) p(t)+\mathcal{G} p(t), \quad t \in J  \tag{79}\\
p(T) \leq 0
\end{array}\right.
$$

where operator $\mathcal{G}$ is defined by

$$
\begin{equation*}
\mathcal{G} p(t)=N(t) p(\alpha(t))+P(t) I_{T}^{q_{1}} p(t) \tag{80}
\end{equation*}
$$

with nonnegative functions $N, P$ integrable on $J$ and the right-sided fractional integral $I_{T}^{q_{1}} p$ of order $q_{1}>0$

In addition, we assume that
$H_{2}: r \leq 1$ with

$$
\begin{equation*}
r=\int_{0}^{T}\left[N(t) \exp \left(\int_{t}^{\alpha(t)} M(s) d s\right)+\frac{P(t)}{\Gamma\left(q_{1}\right)} \int_{t}^{T}(s-t)^{q_{1}-1} \exp \left(\int_{t}^{s} M(\tau) d \tau\right) d s\right] d t \tag{81}
\end{equation*}
$$

Then, $p(t) \leq 0$ on $J$.
Proof. Put

$$
\begin{equation*}
q(t)=\exp \left(\int_{t}^{T} M(s) d s\right) p(t), \quad t \in J \tag{82}
\end{equation*}
$$

This and (79) give $q(T)=p(T) \leq 0$, and

$$
\begin{align*}
q^{\prime}(t) & =\exp \left(\int_{t}^{T} M(s) d s\right)\left[-M(t) p(t)+p^{\prime}(t)\right] \geq \exp \left(\int_{t}^{T} M(s) d s\right) \mathcal{G} p(t) \\
& =N(t) \exp \left(\int_{t}^{\alpha(t)} M(s) d s\right) q(\alpha(t))+\frac{P(t)}{\Gamma\left(q_{1}\right)} \int_{t}^{T}(s-t)^{q_{1}-1} \exp \left(\int_{t}^{s} M(\tau) d \tau\right) q(s) d s \tag{83}
\end{align*}
$$

so

$$
\left\{\begin{align*}
&-q^{\prime}(t) \leq-N(t) \exp \left(\int_{t}^{\alpha(t)} M(s) d s\right) q(\alpha(t))  \tag{84}\\
&-\frac{P(t)}{\Gamma\left(q_{1}\right)} \int_{t}^{T}(s-t)^{q_{1}-1} \exp \left(\int_{t}^{s} M(\tau) d \tau\right) q(s) d s \\
& q(T) \leq 0
\end{align*}\right.
$$

We need to prove that $q(t) \leq 0, t \in J$. Suppose that the inequality $q(t) \leq 0, t \in J$ is not true. Then, we can find $t_{0} \in[0, T)$ such that $q\left(t_{0}\right)>0$. Put

$$
\begin{equation*}
q\left(t_{1}\right)=\min _{\left[t_{0}, T\right]} q(t) \leq 0 \tag{85}
\end{equation*}
$$

Integrating the differential inequality in (84) from $t_{0}$ to $t_{1}$, we obtain

$$
\begin{align*}
q\left(t_{0}\right)-q\left(t_{1}\right) \leq & -\int_{t_{0}}^{t_{1}}\left[N(t) \exp \left(\int_{t}^{\alpha(t)} M(s) d s\right) q(\alpha(t))\right. \\
& \left.+\frac{P(t)}{\Gamma\left(q_{1}\right)} \int_{t}^{T}(s-t)^{q_{1}-1} \exp \left(\int_{t}^{s} M(\tau) d \tau\right) q(s) d s\right] d t  \tag{86}\\
\leq & -r q\left(t_{1}\right) \leq-q\left(t_{1}\right)
\end{align*}
$$

It contradicts the assumption that $q\left(t_{0}\right)>0$. This proves that $q(t) \leq 0$ on $J$. This also proves that $p(t) \leq 0$ on $J$ and the proof is complete.

Remark 5. Assume $M(t) \geq 0$ on $J$ and

$$
\begin{equation*}
\int_{0}^{T}\left[N(t) \exp \left(\int_{t}^{T} M(s) d s\right)+\frac{P(t)}{\Gamma\left(q_{1}\right)} \int_{t}^{T}(s-t)^{q_{1}-1} \exp \left(\int_{t}^{s} M(\tau) d \tau\right) d s\right] d t \leq 1 \tag{87}
\end{equation*}
$$

Note that the above condition does not depend on $\alpha$ and moreover Assumption $H_{2}$ holds.

Remark 6. Assume that $1 \leq A_{0} \exp \left(\int_{s}^{T} M(\tau) d \tau\right)(T-s)^{a}, A_{0}>0, a \geq 0$. Then,

$$
\begin{align*}
r & \leq \int_{0}^{T}\left[N(t) \exp \left(\int_{t}^{\alpha(t)} M(s) d s\right)+\frac{A_{0} P(t)}{\Gamma\left(q_{1}\right)} \exp \left(\int_{t}^{T} M(\tau) d \tau\right) \int_{t}^{T}(s-t)^{q_{1}-1}(T-s)^{a} d s\right] d t \\
& =\int_{0}^{T}\left[N(t) \exp \left(\int_{t}^{\alpha(t)} M(s) d s\right)+\frac{A_{0} P(t) \Gamma(a+1)}{\Gamma\left(a+q_{1}+1\right)} \exp \left(\int_{t}^{T} M(\tau) d \tau\right)(T-t)^{a+q_{1}}\right] d t \equiv r_{1} \tag{88}
\end{align*}
$$

Indeed, Assumption $H_{2}$ holds if $r_{1} \leq 1$.
We can also obtain another condition for $r$ from Assumption $H_{2}$, namely using the following estimation

$$
\begin{equation*}
\exp \left(\int_{0}^{T}|M(\tau)| d \tau\right) \leq P_{0} \tag{89}
\end{equation*}
$$

Then, it is easy to see that Assumption $H_{2}$ holds, if we assume that

$$
\begin{equation*}
\int_{0}^{T}\left[N(t) \exp \left(\int_{t}^{\alpha(t)} M(s) d s\right)+\frac{P(t) P_{0}}{\Gamma\left(q_{1}+1\right)}(T-t)^{q_{1}}\right] d t \leq 1 \tag{90}
\end{equation*}
$$

Now, we are going to use the monotone iterative technique to find a solution of (3) for $q=1$. Let us introduce the following definition.

Let $q=1$ and $q_{1}>0$. We say that $u \in C^{1}(J, \mathbb{R})$ is a lower solution of (3) if

$$
\begin{equation*}
u^{\prime}(t) \leq-F u(t), \quad t \in J, \quad h(u(T)) \leq 0 \tag{91}
\end{equation*}
$$

and it is an upper solution of (3) if the above inequalities are reversed.
A solution $y \in C^{1}(J, \mathbb{R})$ of problem (3) is called maximal if $x(t) \leq y(t), t \in J$ for each solution $x$ of (3), and minimal, if the reverse inequality holds. If both minimal and maximal solutions exist, we call them extremal solutions of (3).

If we know the existence of lower and upper solutions $y_{0}, z_{0}$ of problem (3) such that $z_{0}(t) \leq y_{0}(t), t \in J$, then, under corresponding conditions, we can prove the existence of the extremal solutions of (3) in the sector

$$
\begin{equation*}
\left[z_{0}, y_{0}\right]_{*}=\left\{w \in C^{1}(J, \mathbb{R}): \quad z_{0}(t) \leq w(t) \leq y_{0}(t), \quad t \in J\right\} \tag{92}
\end{equation*}
$$

It is the content of the next result.
Theorem 5. Let $q=1$, and $q_{1}>0$. Let Assumption $H_{1}$ hold (with $g(t)=1$, $t \in J)$ and $h \in C(\mathbb{R}, \mathbb{R})$. Let $y_{0}, z_{0} \in C^{1}(J, \mathbb{R})$ be lower and upper solutions of (3), respectively and $z_{0}(t) \leq y_{0}(t), t \in J$. In addition, we assume that
$H_{3}:$ there exist functions $M \in C(J, \mathbb{R}), N, P \in C\left(J, \mathbb{R}_{+}\right)$such that Assumption
$\mathrm{H}_{2}$ holds and

$$
\begin{aligned}
& f\left(t, v_{1}, v_{2}, v_{3}\right)-f\left(t, u_{1}, u_{2}, u_{3}\right) \geq-M(t)\left[v_{1}-u_{1}\right]-N(t)\left[v_{2}-u_{2}\right]-P(t)\left[v_{3}-u_{3}\right] \\
& \quad \text { if } z_{0}(t) \leq u_{1} \leq v_{1} \leq y_{0}(t), z_{0}(\alpha(t)) \leq u_{2} \leq v_{2} \leq y_{0}(\alpha(t)), I_{T}^{q_{1}} z_{0}(t) \leq u_{3} \leq v_{3} \leq \\
& I_{T}^{q_{1}} y_{0}(t)
\end{aligned}
$$

$H_{4}$ : there exists a constant $\mu>0$ such that

$$
\begin{equation*}
h(u)-h\left(u_{0}\right) \leq \mu\left(u_{0}-u\right) \text { if } z_{0}(T) \leq u \leq u_{0} \leq y_{0}(T) \tag{94}
\end{equation*}
$$

Then, problem (3) has extremal solutions in the sector $\left[z_{0}, y_{0}\right]_{*}$.
Proof. Put $\left(z_{0}, y_{0}\right)_{*}=\left\{w \in C(J, \mathbb{R}): \quad z_{0}(t) \leq w(t) \leq y_{0}(t), t \in J\right\}$. Let $\eta, \xi \in\left(z_{0}, y_{0}\right)_{*}$ and let $\varphi(t)=\min [\eta(t), \xi(t)], \Phi(t)=\max [\eta(t), \xi(t)]$.

Consider the boundary value problems

$$
\begin{align*}
& \left\{\begin{array}{l}
v^{\prime}(t)=M(t)[v(t)-\Phi(t)]+\mathcal{G} v(t)-\mathcal{G} \Phi(t)-F \Phi(t), \quad t \in J \\
v(T)=\frac{1}{\mu} h(\Phi(T))+\Phi(T)
\end{array}\right.  \tag{95}\\
& \left\{\begin{array}{l}
w^{\prime}(t)=M(t)[w(t)-\varphi(t)]+\mathcal{G} w(t)-\mathcal{G} \varphi(t)-F \varphi(t), \quad t \in J \\
w(T)=\frac{1}{\mu} h(\varphi(T))+\varphi(T)
\end{array}\right. \tag{96}
\end{align*}
$$

where operator $\mathcal{G}$ is defined as in Lemma 3. By Theorem 2, problems (95), (96) have a unique solution. Therefore, we can define the operator

$$
\begin{equation*}
B: \bar{\Omega} \rightarrow C(J, \mathbb{R}) \times C(J, \mathbb{R}), \quad\left(z_{0}, y_{0}\right)_{*} \subset C(J, \mathbb{R}), B(\eta, \xi)=(v, w) \tag{97}
\end{equation*}
$$

where $v, w$ are solutions of (95) and (96), respectively with $\bar{\Omega}=\left(z_{0}, y_{0}\right)_{*} \times\left(z_{0}, y_{0}\right)_{*}$.
Now, we want to show that

$$
\begin{equation*}
z_{0}(t) \leq w(t) \leq v(t) \leq y_{0}(t), \quad t \in J \tag{98}
\end{equation*}
$$

Put $p=z_{0}-w$. Then, in view of Assumption $H_{3}$, we have

$$
\begin{align*}
p^{\prime}(t) & \geq-F z_{0}(t)-M(t)[w(t)-\varphi(t)]-\mathcal{G} w(t)+\mathcal{G} \varphi(t)+F \varphi(t) \\
& \geq-M(t)\left[\varphi(t)-z_{0}(t)\right]-\mathcal{G} \varphi(t)+\mathcal{G} z_{0}(t)-\mathcal{G} w(t)+\mathcal{G} \varphi(t)-M(t)[w(t)-\varphi(t)] \\
& =M(t) p(t)+\mathcal{G} p(t) \tag{99}
\end{align*}
$$

Moreover, in view of Assumption $H_{4}$,

$$
\begin{align*}
p(T) & =z_{0}(T)-\frac{1}{\mu}\left[h(\varphi(T))-h\left(z_{0}(T)\right)+h\left(z_{0}(T)\right)\right]-\varphi(T)  \tag{100}\\
& \leq z_{0}(T)-\varphi(T)+\varphi(T)-z_{0}(T)=0
\end{align*}
$$

This and Lemma 3 show that $z_{0}(t) \leq w(t), t \in J$. Similarly we can show that $v(t) \leq y_{0}(t), t \in J$. To show that $w(t) \leq v(t), t \in J$, we put $p=w-v$. Then,

$$
\begin{align*}
p^{\prime}(t)= & M(t)[w(t)-\varphi(t)-v(t)+\Phi(t)]+\mathcal{G} w(t)-\mathcal{G} \varphi(t)-F \varphi(t)-\mathcal{G} v(t) \\
& +\mathcal{G} \Phi(t)+F \Phi(t) \\
\geq & -M(t)[\Phi(t)-\varphi(t)]-\mathcal{G} \Phi(t)+\mathcal{G} \varphi(t)+M(t)[w(t)-\varphi(t)-v(t)+\Phi(t)] \\
& +\mathcal{G} w(t)-\mathcal{G} \varphi(t)-\mathcal{G} v(t)+\mathcal{G} \Phi(t) \\
= & M(t) p(t)+\mathcal{G} p(t) \tag{101}
\end{align*}
$$

Moreover

$$
\begin{equation*}
p(T)=\frac{1}{\mu} h(\varphi(T))+\varphi(T)-\frac{1}{\mu} h(\Phi(T))-\Phi(T) \leq 0 \tag{102}
\end{equation*}
$$

Hence $B: \bar{\Omega} \rightarrow \bar{\Omega}$.

Note that operator $B: \bar{\Omega} \rightarrow \bar{\Omega}$ is compact by direct application of ArzeliAscoli theorem. Hence, by Schauder's fixed point theorem, the operator $B$ has a fixed point, i.e. there exist $(v, w) \in \bar{\Omega}$ such that $B(v, w)=(v, w)$ and $w \leq v$.

Now, by (95) and (96), we see that $v, w$ satisfy the following relations

$$
\begin{gather*}
\left\{\begin{array}{l}
v^{\prime}(t)=M(t)[v(t)-v(t)]+\mathcal{G} v(t)-\mathcal{G} v(t)-F v(t), \quad t \in J \\
v(T)=\frac{1}{\mu} h(v(T))+v(T)
\end{array}\right.  \tag{103}\\
\left\{\begin{array}{l}
w^{\prime}(t)=M(t)[w(t)-w(t)]+\mathcal{G} w(t)-\mathcal{G} w(t)-F w(t), \quad t \in J \\
w(T)=\frac{1}{\mu} h(w(T))+w(T)
\end{array}\right. \tag{104}
\end{gather*}
$$

It shows that $v, w \in C^{1}(J)$ are solutions of problem (3). This ends the proof.

## 7. Existence results for fractional problems of type (3) with $q \in(0,1)$

In this Section, we will use the monotone iterative method to show that problem (3) with $q_{1}>0,0<q<1$ has a solution. First, we cite some comparison results.

Lemma 4 (see [21]). Let $q \in(0,1), M \in C\left(J,\left[0, \mathbb{R}_{+}\right)\right.$. Suppose that $p \in$ $C_{1-q}(J, \mathbb{R})$ satisfies the problem:

$$
\left\{\begin{array}{l}
D_{T}^{q} p(t) \leq-M(t) p(t), \quad t \in J_{0}  \tag{105}\\
\bar{p}(T) \leq 0
\end{array}\right.
$$

Then, $p(t) \leq 0$ on $J$.
Lemma 5 (see [21]). Let $q \in(0,1), M \in \mathbb{R}$. Suppose that $p \in C_{1-q}(J, \mathbb{R})$ satisfies the problem:

$$
\left\{\begin{array}{l}
D_{T}^{q} p(t) \leq-M p(t), \quad t \in J_{0}  \tag{106}\\
\bar{p}(T) \leq 0
\end{array}\right.
$$

Then, $p(t) \leq 0$ on $J$.
Now, we introduce the following definition.
Let $q_{1}>0,0<q<1$. We say that $u \in C_{1-q}(J, \mathbb{R})$ is a lower solution of (3) if

$$
\begin{equation*}
D_{T}^{q} u(t) \leq F u(t), \quad t \in J_{0}, \quad h(\bar{u}(T)) \leq 0 \tag{107}
\end{equation*}
$$

and it is an upper solution of (3), if the above inequalities are reversed.
Theorem 6. Let $q_{1}>0,0<q<1$. Let Assumption $H_{1}$ hold (with $g(t)=$ $1, t \in J)$ and $h \in C(\mathbb{R}, \mathbb{R})$. Let $y_{0}, z_{0} \in C_{1-q}(J, \mathbb{R})$ be lower and upper solutions of (3), respectively and $y_{0}(t) \leq z_{0}(t), t \in J$. In addition, we assume that
$H_{5}$ : there exist a function $M \in C\left(J, \mathbb{R}_{+}\right)$such that

$$
f\left(t, u_{1}, u_{2}, u_{2}\right)-f\left(t, v_{1}, v_{2}, v_{3}\right) \leq M(t)\left[v_{1}-u_{1}\right]
$$

if $y_{0}(t) \leq u_{1} \leq v_{1} \leq z_{0}(t), y_{0}(\alpha(t)) \leq u_{2} \leq v_{2} \leq z_{0}(\alpha(t)), I_{T}^{q_{1}} y_{0}(t) \leq u_{3} \leq v_{3} \leq$ $I_{T}^{q_{1}} z_{0}(t)$,
$H_{6}$ : there exists a constant $\mu>0$ such that

$$
\begin{equation*}
h\left(u_{0}\right)-h(u) \leq \mu\left(u_{0}-u\right) \text { if } \bar{y}_{0}(T) \leq u \leq u_{0} \leq \bar{z}_{0}(T) \tag{109}
\end{equation*}
$$

Then, problem (3) has extremal solutions in the sector

$$
\begin{equation*}
\left[y_{0}, z_{0}\right]=\left\{w \in C_{1-q}(J, \mathbb{R}): y_{0}(t) \leq w(t) \leq z_{0}(t), t \in J_{0}, \bar{y}_{0}(T) \leq \bar{w}(T) \leq \bar{z}_{0}(T)\right\} \tag{110}
\end{equation*}
$$

Proof. Let

$$
\begin{align*}
& \begin{cases}D_{T}^{q} y_{n+1}(t)=F y_{n}(t)-M(t)\left[y_{n+1}(t)-y_{n}(t)\right], & t \in J_{0} \\
\bar{y}_{n+1}(T)=-\frac{1}{\mu} h\left(\bar{y}_{n}(T)\right)+\bar{y}_{n}(T)\end{cases}  \tag{111}\\
& \begin{cases}D_{T}^{q} z_{n+1}(t)=F z_{n}(t)-M(t)\left[z_{n+1}(t)-z_{n}(t)\right], & t \in J_{0} \\
\bar{z}_{n+1}(T)=-\frac{1}{\mu} h\left(\bar{z}_{n}(T)\right)+\bar{z}_{n}(T)\end{cases} \tag{112}
\end{align*}
$$

for $n=0,1, \cdots$. Note that problems (111) and (112) have a unique solution, in view of Theorem 1.

Put $p=y_{0}-y_{1}$. Then,

$$
\begin{align*}
D_{T}^{q} p(t) & \leq F y_{0}(t)-F y_{0}(t)+M(t)\left[y_{1}(t)-y_{0}(t)\right]=-M(t) p(t) \\
\bar{p}(T) & =\bar{y}_{0}(T)+\frac{1}{\mu} h\left(\bar{y}_{0}(T)\right)-\bar{y}_{0}(T) \leq 0 \tag{113}
\end{align*}
$$

Hence, $y_{0}(t) \leq y_{1}(t)$, in view of Lemma 4. Similarly, $z_{1}(t) \leq z_{0}(t)$. Put $p=y_{1}-z_{1}$. Then,

$$
\begin{align*}
D_{T}^{q} p(t) & =F y_{0}(t)-M(t)\left[y_{1}(t)-y_{0}(t)\right]-F z_{0}(t)+M(t)\left[z_{1}(t)-z_{0}(t)\right] \\
& \leq M(t)\left[z_{0}(t)-y_{0}(t)\right]-M(t)\left[y_{1}(t)-y_{0}(t)-z_{1}(t)+z_{0}(t)\right]=-M(t) p(t) \\
\bar{p}(T) & =-\frac{1}{\mu} h\left(\bar{y}_{0}(T)\right)+\bar{y}_{0}(T)+\frac{1}{\mu} h\left(\bar{z}_{0}(T)\right)-\bar{z}_{0}(T) \\
& \leq \bar{z}_{0}(T)-\bar{y}_{0}(T)+\bar{y}_{0}(T)-\bar{z}_{0}(T)=0 \tag{114}
\end{align*}
$$

by Assumptions $H_{5}, H_{6}$. This proves that

$$
\begin{equation*}
y_{0}(t) \leq y_{1}(t) \leq z_{1}(t) \leq z_{0}(t), \quad t \in J \tag{115}
\end{equation*}
$$

Now, we prove that $y_{1}$ is a lower solution of problem (3). Indeed,

$$
\begin{align*}
D_{T}^{q} y_{1}(t) & =F y_{0}(t)-M(t)\left[y_{1}(t)-y_{0}(t)\right]-F y_{1}(t)+F y_{1}(t) \\
& \leq M(t)\left[y_{1}(t)-y_{0}(t)\right]-M(t)\left[y_{1}(t)-y_{0}(t)\right]+F y_{1}(t)=F y_{1}(t) \\
\bar{y}_{1}(T) & =-\frac{1}{\mu}\left[h\left(\bar{y}_{0}(T)\right)-h\left(\bar{y}_{1}(T)\right)+h\left(\bar{y}_{1}(T)\right)\right]+\bar{y}_{0}(T)  \tag{116}\\
& \leq \bar{y}_{1}(T)-\bar{y}_{0}(T)+\bar{y}_{0}(T)-h\left(\bar{y}_{1}(T)\right)
\end{align*}
$$

so $h\left(\bar{y}_{1}(T)\right) \leq 0$. This proves that $y_{1}$ is a lower solution of problem (3). Similarly, we can show that $z_{1}$ is an upper solution of (3).

By induction, we can prove that

$$
\begin{equation*}
y_{0}(t) \leq y_{1}(t) \leq \cdots \leq y_{n}(t) \leq z_{n}(t) \leq \cdots \leq z_{1}(t) \leq z_{0}(t), \quad t \in J \tag{117}
\end{equation*}
$$

Sequences $\left\{y_{n}\right\},\left\{z_{n}\right\}$ are monotone. It is easy to show that they converge to $y$ and $z$, respectively, and $y \leq z$. Indeed, there is no problem to prove that problem (3) has minimal and maximal solutions in $\left[y_{0}, z_{0}\right]$. This ends the proof.

Remark 7. If we extra assume that $M(t)=0, t \in J$, then, $f$ is nondecreasing with respect to the last three variables.

Remark 8. If condition (108) holds for $\bar{M} \in C(J, \mathbb{R})$, then, it is also satisfied for some $M \in C\left(J, \mathbb{R}_{+}\right)$.

Example 5. Consider the problem:

$$
\left\{\begin{array}{l}
D_{T}^{q} x(t)=A e^{-x(t)}+B x(\alpha(t))+C I_{T}^{q_{1}} x(t)+\frac{D}{\sqrt{\pi(1-t)}} \equiv F x(t), \quad t \in J_{0}  \tag{118}\\
0=\bar{x}(1)[1-\bar{x}(1)]
\end{array}\right.
$$

where $J_{0}=[0,1), q=\frac{1}{2}, q_{1}>0, \alpha \in C([0,1],[0,1]), \alpha(t) \geq t$. Moreover, we assume that $A, B, C, D \geq 0$ and such that

$$
\begin{align*}
& A e^{-1}+2 B+C(1-t)^{q_{1}}\left[\frac{1}{\Gamma\left(q_{1}+1\right)}+\frac{1-t}{\Gamma\left(q_{1}+2\right)}\right]+\frac{D}{\sqrt{\pi(1-t)}} \\
& \quad \leq \frac{1}{\sqrt{\pi(1-t)}}+\frac{2}{\sqrt{\pi}} \sqrt{1-t}, \quad t \in[0,1) \tag{119}
\end{align*}
$$

Put $y_{0}(t)=0, z_{0}(t)=2-t$, so $\bar{y}_{0}(1)=\bar{z}_{0}(1)=0$. Note that $M(t)=A e^{2}, \mu=1$, from Theorem 6. Indeed, $y_{0}$ is a lower solution of problem (118). Moreover,

$$
\begin{align*}
F z_{0}(t) & =A e^{-(2-t)}+B(2-\alpha(t))+\frac{C}{\Gamma\left(q_{1}\right)} \int_{t}^{T}(s-t)^{q_{1}-1}(1+1-s) d s+\frac{D}{\sqrt{\pi(1-t)}} \\
& \leq A e^{-1}+2 B+C(1-t)^{q_{1}}\left[\frac{1}{\Gamma\left(q_{1}+1\right)}+\frac{1-t}{\Gamma\left(q_{1}+2\right)}\right]+\frac{D}{\sqrt{\pi(1-t)}}  \tag{120}\\
& \leq \frac{1}{\sqrt{\pi(1-t)}}+\frac{2}{\sqrt{\pi}} \sqrt{1-t}=D_{T}^{q} z_{0}(t)
\end{align*}
$$

in view of (119). This proves that $z_{0}$ is an upper solution of problem (118). Hence, problem (118) has extremal solutions in the region $\left[y_{0}, z_{0}\right]$, by Theorem 6.

Remark 9. We can also discuss the problem with more right-sided fractional integrals, namely

$$
\left\{\begin{array}{l}
D_{T}^{q} x(t)=f\left(t, x(t), x(\alpha(t)), I_{T}^{q_{1}} x(t), I_{T}^{q_{2}} x(t), \cdots, I_{T}^{q_{r}} x(t)\right), \quad t \in J_{0}  \tag{121}\\
0=h(\bar{x}(T))
\end{array}\right.
$$

with $q_{1}, q_{2}, \cdots, q_{r}>0$.

## References

[1] Kilbas A A, Srivastava R H and Trujillo J J 2006 Theory and Applications of Fractional Differential Equations, North-Holland Mathematics Studies, Elsevier, 204
[2] Al-Bassam M A 1965 J. Reine Angew. Math. 21870
[3] Jankowski T 2008 Dynam. Systems Appl. 17677
[4] Jankowski T 2013 Appl. Math. Lett. 26344
[5] Jankowski T 2013 Appl. Math. Comput. 2197772
[6] Jankowski T 2013 Appl. Math. Comput. 2199155
[7] Kilbas A A, Bonilla B and Trukhillo Kh 2000 Dokl. Nats. Akad. Nauk Belarusi 4418 (Russian)
[8] Kilbas A A and Marzan A S 2003 Dokl. Nats. Akad. Nauk Belarusi 4729 (Russian)
[9] Lakshmikantham V, Leela S and Vasundhara J 2009 Theory of Fractional Dynamic Systems, Cambridge Academic Publishers
[10] Lin L, Liu X and Fang H 2012 Elektron. J. Differential Equations 1001
[11] Liu Z, Wang R 2013 Abstr. Appl. Anal., Art. ID 432941
[12] Liu Z, Sun J, Szántó I 2013 Results Math 631277
[13] McRae A F 2009 Nonlinear Anal. 716093
[14] Ramirez D J and Vatsala S A 2009 Opuscula Math. 29289
[15] Samko G S, Kilbas A A and Marichev I O 1993 Fractional Integrals and Derivatives: Theory and Applications, Gordon and Breach Science Publishers
[16] Wang G 2012 J. Comput. Appl. Math. 2362425
[17] Wang G, Liu S, Baleanu D and Zhang L 2013 Adv. Difference Equ. 2013:280
[18] Wei Z, Li G and Che J 2010 J. Math. Anal. Appl. 367260
[19] Zhang S 2009 Nonlinear Anal. 712087
[20] Zhang S and Su X 2011 Comput. Math. Appl. 621269
[21] Jankowski T 2014 Appl. Math. Lett. 2814

